

















Datasheet

Distec

SmartLED-IVB

45W LED Backlight Converter

ZU-09-038



Version 1.2

07.10.2022

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1 Revision History

Date	Rev.No.	Description	
09.03.2021	1.0	Initial version	All
25.06.2021	1.1	Derating added.	8
		Minimum Input Voltage 10V	6,9
		Master/Slave feature removed	
07.10.2022	1.2	General Features corrected	

2 Overview

SmartLED-IVB is a 45W output LED backlight converter able to drive up to four rails of high-brightness LEDs. The converter is highly configurable by software and thus can be adapted to a multitude of different applications.

SmartLED-IVB is intended as a universal LED Converter to drive LCD panel backlight systems (LED rails) with easy configuration for low and mid quantity sales projects to have a cheaper and/or adaptable product as compared to Mitsubishi (TDK), PowerSystems, CCBR/CDS converter.

To compete with these already available products, the SmartLED-IVB shall have all the functionality that SmartLED-II and SmartLED-III have. Additionally, SmartLED-IVB will allow design of LED rails with higher voltage and higher power.

Less warehouse management and faster kit integration with one adaptable HW.

3 Warnings

Although the SmartLED-IVB is using protection circuits for most of its interfaces, it is strongly recommended to adhere to the maximum ratings of SmartLED-IVB, outlined in this document.

4 General Features

- Input: 10 28V
- Output: 30 56V, 30mA 300mA per channel (rail), total current limited to 1,2A, total power limited to approx. 45W
- Output: supports single, dual, triple and quad rails at a voltage/current rating of 30–56 V at 30–300 mA per rail.
- Outputs can be paralleled using cable adapter or as an assembly option for high-current applications.
- Control via analog voltage (0..3.3V or 0..5V) or PWM (100 .. 1000Hz)
- Output PWM synchronized to input, sync signal or free running with programmable frequency.
- I2C for ambient light sensor and temperature sensor(s) (implemented in hardware, firmware support on customer request)
- Additional GPIOs for local control (pushbuttons, sensor pads or potentiometer) of brightness (implemented in hardware, firmware support on customer request)
- Control input for night vision (NVIS) mode (implemented in hardware, firmware support on customer request)
- Error flag to detect failure of power stage or LED rail.
- LED brightness control by PWM dimming for stable color temperature; optionally, use current control or combined dimming for brightness control.
- Wide dimming range up to 1:14000 (depends on PWM frequency)
- Control characteristic curve can be adapted upon customer request; currently, linear and exponential curve is configurable.
- Firmware-controlled compensation circuit for flicker-free operation in a wide output load range.

Some features require specific firmware support or are mutually exclusive to other features. Please contact your sales partner to discuss possible options or combinations.

Features will be configured by different firmware and/or configuration files. For high-volume applications, a version without microprocessor control may be possible as a more economical solution – please contact your sales partner to discuss this as a project-based solution.

Configuration via serial port + software ("SmartLEDRover") is implemented. Serial port control is also possible, but subject to restrictions to avoid interfering with the protocol used for factory programming/configuration.

5 Hardware Features

High-Efficiency Boost Regulator

- 10 28V input voltage range (continuous operation below 14V is subject to output power derating; input current must not exceed 4A continuously)
- Max. 300mA output current per channel (depending on actual rail configuration due to total current and power limit)
- Efficiency >= 86%, typically 92%

Flexible Microcontroller Control

- On-Board microcontroller handles all input and control signals.
- Features are defined by firmware.

Improved Output Channel Control

- Improved brightness stepping from 0 to 100% brightness.
- Exponential control characteristic available as standard and configurable via configuration
- Arbitrary control characteristic in addition to the standard configurable linear and exponential characteristics can be realized in software – please contact your sales partner to discuss possibilities.
- Individually control output channels On/Off and current regulation for different modes, e.g., night vision (NVIS):
 - Channels can be programmed to different max. current levels.
 - However, no different current levels possible at the same time
 - Control input pin shared with sync input is used to switch over between active channels with their respective current level.

Ambient Light Sensor

• Support for ambient light sensor via I2C

Temperature Sensor

- Internal temperature sensor in controller on SmartLED-IVB
- External temperature Sensor(s) are supported via I2C.
- Two I2C channels are available to allow connection of identical sensors (e.g., for identical sensors on both rails)

Output Fault Checking

- Faulty rails are disabled.
- Correctly working rails continue to operate.
- Error flag signals faulty rails (short circuit as well as broken wires)

Not all hardware features are already supported by firmware, especially connecting sensors is considered in the hardware but there is no firmware support in place yet. Please discuss possibilities for firmware adaptation with your sales partner.

6 Application Diagram and User Controls

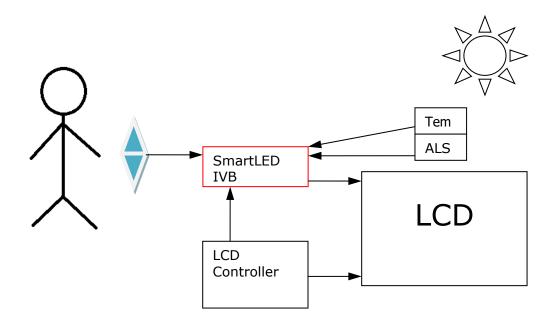


Figure-1: Overview of SmartLED-IVB usage (ALS = ambient light sensor)

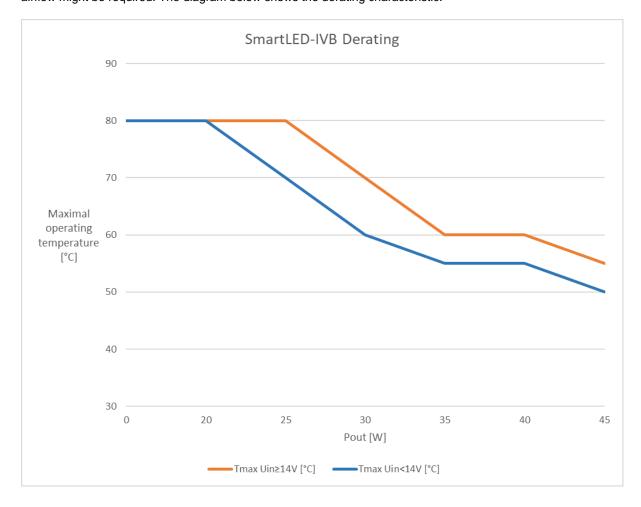
7 Absolute Maximum Ratings

Permanent damage to the device may occur if maximum values are exceeded!

Item	Symbol	Min.	Max.	Unit	Note
Supply Voltage	Vin	-0.3	28	VDC	1
Control Voltages	VENABLE, VCONTROL, VSYNC	-1.0	6.0	V	
Storage Temperature	T _{St}	-40	+105	°C	
Operating Temperature	Top	-30	+80	°C	2

Note (1) Within operating temperature range.

Note (2) In the upper range of T_{OP} total output power as well as the heat dissipation/cooling has to be checked. Forced airflow might be required. The diagram below shows the derating characteristic:



8 Electrical Specification

ITEM	SYMBOL	MIN.	TYP.	MAX.	UNIT	Remarks
Supply Voltage V _{IN}		10	12	28	V	6)
Efficiency		86	92		%	
Min. ON Level Voltage	VCONTROL (PWM mode), VENABLE	1.6		5.0	V	
Max. OFF Level Voltage	VCONTROL (PWM mode), VENABLE	0		0.6	V	
				5	V	IRAIL = max.
Brightness control voltage	VCONTROL (analog mode)			3.3	V	Note 1)
	,	0			V	IRAIL = min. Note 2)
PWM frequency	F _{PWM}	100	225	1000	Hz	
Dimming	V _{PWMIN}	0		100	%	Note 1), 2)
Input pulse width	T _{PWI}	90			μs	Note 7)
Output pulse width	T _{PWO}	0.7		T _{PWI}	μs	Note 8)
PWM voltage	V _{PWMIN}	0	3.3	5.0	V	
IRAIL LED rail current	I _{RAIL}	30		300	mA	V _{CONTROL} = max V _{PWMIN} = 100% Note 4)
Total output current	I _{TOTAL}			1,2	А	Sum of active channels
VRAIL LED rail forward voltage	Vrail	30		56.0	V	
Total output power	P _{total}	2		45	W	Note 4)
Evror Floa	V _E ,High	2.3		3.3	V	10mA max, Note 5, 9)
Error Flag	V _{E,Low}	0			V	Note 5, 9)

Notes:

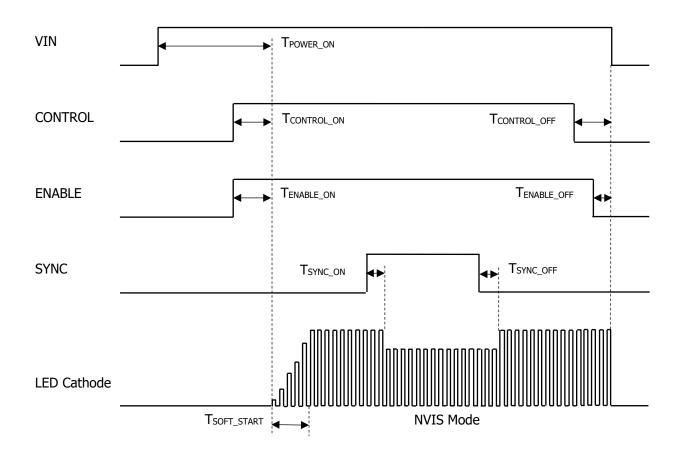
- 1) PWM dimming or analog dimming can be selected via SmartLED Rover.
- 2) Error Flag might be unavailable for very low dimming ratio (< 10%, TBD)
- To use sync input requires alternative firmware. Please contact your sales partner for possible options.
- 4) Maximum output current limited by maximum output power depending on rail voltage.
- 5) Error flag uses a PNP open-collector output with a 100R current limiting resistor. As such, the pin cannot sink any current; the current sourced from this pin must not exceed 10 mA for the minimum output voltage to be achieved.
- 6) Maximum continuous input current is 4A; if the converter is to be operated at a lower voltage than 14V continuously, the maximum output power must be derated accordingly.
- 7) Do not fall below that value to prevent flicker.
- 8) Use the Brightness Input / Output Transfer Characteristic feature of SmartLED Rover for diming the brightness to 0nits with smooth transition and achieving the dimming range up to 1:14000@100Hz.

9) SmartLED monitors the LED strings to detect LED short-circuit and string open-circuit faults. When verified, all string faults force the ERROR flag and the red LED active. As well, only the fault strings are deactivated and remain disabled until toggling ENABLE low and then high.

Currently, there is not an ERROR flag connection between SmartLED and Prisma, because Prisma does not provide a suitable input to monitor this signal.

Standard settings	Settings for smooth transition
Brightness Input / Output Transfer Characteristic out = in ^ (1 + 0	Brightness Input / Output Transfer Characteristic out = in ^ (1 + 15 / 8)

8.1 Power Sequencing



ITEM	SYMBOL	MIN.	TYP.	MAX.	UNIT	Remarks
Power ON time delay	Tpower_on	1200	1300	1400	ms	Vcontrol = max Venable = max
Soft Start duration	ISOFT START 200 300 400 MS		Vcontrol = max Venable = max			
ENABLE ON time delay	T _{ENABLE_} ON	50	100	150	ms	V _{CONTROL} = max
ENABLE OFF time delay	Tenable_off	5	10	20	ms	V _{CONTROL} = max
CONTROL ON time delay	Tcontrol_on	50	100	150	ms	V _{ENABLE} = max
CONTROL OFF time delay	T _{CONTROL_OFF}	20	30	40	ms	V _{ENABLE} = max
SYNC ON/OFF time delay for NVIS control	Tsync_on/off	5	10	20	ms	V _{CONTROL} = max V _{ENABLE} = max

Note:

The LED Cathode voltage is measured on a shunt resistor connected to the ground and reflects the rail current.

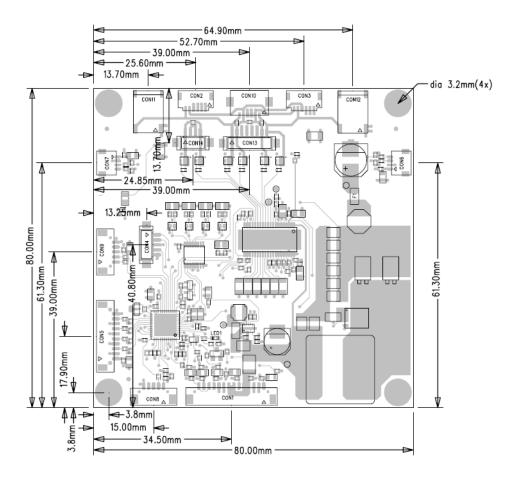
9 Mechanical Specification

ITEM	DESCRIPTION	REMARKS
Length	80 mm	± 0.2 mm
Width	80 mm	± 0.2 mm
Height (top side)	7 mm	± 0.2 mm
Height (PCB)	1.6 mm	± 0.1 mm
Height (bottom	0 mm	No components or wires on
side)		bottom side
Weight	42 g	

9.1 Mounting Hole Specification

ITEM	DESCRIPTION	REMARKS
Quantity	4	
Inner Diameter	3.2 mm	± 0.1 mm
Outer Diameter	6.8 mm	± 0.1 mm
Copper Plating	0.035 mm	± 0.01 mm
Gold Finish	0.05 μm	± 0.02 μm

The mechanical layout is made similar to current SmartLED-IVA connector placement, but due to the higher power additional board space for cooling is needed.



10 Connectors and Switches

The drawing above shows the input and output interfaces of the SmartLED-IVB. The design is implemented as a single printed circuit board.

10.1 Overview

CON	DESCRIPTION	TYPE	MANUFACTURER	Notes
CON1	CON1 Power supply and control DF13-14P		Hirose	
CON2	Rail 2-4 output	SM06B-SHLS-TF	JST	
CON3	Rail 1-3 output	SM06B-SHLS-TF	JST	
CON4	Factory Programming/Debug	DF13-5P-1.25V	Hirose	
CON5	GPIO / User Interface	DF13-10P-1.25H	Hirose	
CON6	I ² C-0	501331-0407	Molex	
CON7	I ² C-1	501331-0407	Molex	
CON8	Master/Slave Connector	-	-	Not Available
CON9	Serial interface	DF13-5P-1.25H	Hirose	
CON10	Rail 1-4 output	FH12-6S-1SH	Molex	
CON11	Rail 4 output	SM02B-BHSS-1-TB	JST	Assembled only on request
CON12	Rail 1 output	SM02B-BHSS-1-TB	JST	
CON13	Rail 1-4 output	DF13-8P-1.25V	Hirose	
CON14	Rail 5-6 output	DF13-4P-1.25V	Hirose	

10.2 Input Connectors

10.2.1 Input Power/Control Connector

Location: CON1

Connector used: DF13-14P-1.25H (20) (Hirose)
Mating housing: DF13-14S-1.25C (Hirose)

Function:

Pin No.	Symbol	Function	Note
1	ERROR	ERROR Flag (high = Error)	
2	GND	Power return	
3	GND	Power return	
4	VIN	+12VDC input power	
5	VIN	+12VDC input power	
6	SYNC	External Sync input /	2
		NVIS mode select	
7	VIN	+12VDC input power	
8	VIN	+12VDC input power	
9	GND	Power return	
10	GND	Power return	
11	ENABLE	On/Off control	
12	CONTROL	Brightness control voltage	1
		(0-5VDC or PWM)	
13	+3.3V	Power output	3
14	CONTROL	Brightness control voltage	1
		(0-5VDC or PWM)	

Notes:

- To use voltage or PWM control of dimming requires alternative firmware. Please contact your sales partner for specific information about possible options. Pins 12 and 14 are connected internally but kept for backwards compatibility.
- 2) To use sync input or NVIS mode feature requires alternative firmware. Please contact your sales partner for possible options.
- 3) Output power for supply of analog dimming potentiometer; kept for compatibility, use of GPIO/User Interface for new designs is recommended.

10.3 Output Connectors

10.3.1 LED Rail Connectors

Location: CON13

Connectors used: Hirose DF13-8P-1.25V Mating housing: Hirose DF13-8S-1.25C

Function:

Pin No.	Symbol	Function
1		LED Cathode Rail 4
2		LED Cathode Rail 3
3		LED Common Anode
4		LED Common Anode
5		LED Common Anode
6		LED Common Anode
7		LED Cathode Rail 2
8		LED Cathode Rail 1

Location: CON14

Connectors used: Hirose DF13-4P-1.25V Mating housing: Hirose DF13-4S-1.25C

Function:

Pin No.	Symbol	Function
1		LED Cathode Rail 5
2		LED Common Anode
3		LED Common Anode
4		LED Cathode Rail 6

Location: CON10

Connectors used: Hirose FH12-6S-1SH

Mating housing: none (FFC Connector, 6-pin, 1 mm pitch)

Function:

Pin No.	Symbol Function	
1	LED Cathode Rail 1	
2	LED Cathode Rail 2	
3	LED Common Anode	
4	LED Common Anode	
5		LED Cathode Rail 3
6	LED Cathode Rail 4	

Location: CON11

Connectors used: JST SM02B-BHSS-1-TB Mating housing: JST BHSR-02VS-01(N)

Function:

Pin No.	Pin No. Symbol Function	
1	LED Anode	
2		LED Cathode Rail 4

Location: CON12

Connectors used: JST SM02B-BHSS-1-TB Mating housing: JST BHSR-02VS-01(N)

Function:

Pin No.	. Symbol Function		
1	LED Anode		
2		LED Cathode Rail 1	

Location: CON2

Connectors used: JST SM06B-SHLS-TF Mating housing: JST SHLP-06V-S-B

Function:

Pin No.	Symbol	l Function	
1	LED Common Anode		
2	LED Common Anode		
3	LED Common Anode		
4		LED Cathode Rail 2	
5	LED Cathode Rail 3		
6	LED Cathode Rail 4		

Location: CON3

Connectors used: JST SM06B-SHLS-TF Mating housing: JST SHLP-06V-S-B

Function:

Pin No. Symbol		Function	
1		LED Common Anode	
2		LED Common Anode	
3		LED Common Anode	
4	LED Cathode Rail 3		
5	LED Cathode Rail 1		
6	LED Cathode Rail 2		

Outputs can be paralleled using cable adapter or as an assembly option for high-current applications.

10.4 Other Connectors

10.4.1 I²C (Temperature/Light Sensor) connector

Location: CON6, CON7

Connector used: 501568-0407 (Molex)

Mating housing: 501330-0400

Function:

Pin No. Symbol		Function	
1	+3.3V Sensor S		
2	2 GND Ground		
3	SCL	clock	
4	SDA	A data	

Two separate I²C channels are used to allow two identical temperature sensors (e.g. mounted on the LED rails) to be used without the need for address selection.

Please contact your sales partner for possible firmware modifications to use an ambient light or temperature sensor.

10.4.2 User Interface/GPIO Connector

GPIO pulled out externally via connector to allow for brightness adjustment using external controls.

GPIO pins can be used for keypad (push button or sensor key) as well as analog input for potentiometer. 3.3V supply for potentiometer or external logic is available on user interface connector. Each GPIO pin can be individually configured as a digital GPIO, A/D converter input (ADC) or touch sensing input (TSI). Standard firmware does not include support for this connector; please contact your sales partner for possible options.

Location: CON5

Connector used: DF13-10P-1.25H (20) (Hirose)
Mating housing: DF13-10S-1.25C (Hirose)

Function:

Pin No.	Symbol	Function	Note
1	V3.3V	+3.3VDC output power	1)
2	GND	Power return/shield	
3	GPIO1	GPIO/ADC/TSI	2)
4	GND	Power return/shield	
5	GPIO2	GPIO/ADC/TSI	2)
6	GND	Power return/shield	
7	GPIO3	GPIO/ADC/TSI	2)
8	GND	Power return/shield	
9	GPIO4	GPIO/ADC/TSI	2)
10	GND	Power return/shield	

Notes:

- 1) Maximum current drawn 300mA
- 2) Pin function is software defined; contact your sales partner for possible options.

10.4.3 Master/Slave Connector (Not Available)

In contrast to SmartLED-IV, Smart LED-IVB is not supporting Master/Slave function.

Location: CON8

10.4.4 Serial Interface Connector

The serial interface connector is used for factory programming and can also be used for field firmware or configuration upgrade. The signals are 3,3V TTL/CMOS level. For special applications, a serial control channel can also be implemented in firmware upon request. Please contact your sales partner to discuss further options.

Location: CON9

Connector used: DF13-5P-1.25H (20) (Hirose)
Mating housing: DF13-5S-1.25C (Hirose)

Function:

Pin No.	Symbol	Function	Note
1	TXD	Transmit data from SmartLED-IVB	1)
2	RXD	Receive Data to SmartLED-IVB	1)
3	+3,3V	3,3V power supply for e.g. level converter	
4	NC	No Connection	
5	GND	Ground/Shield	

Notes:

1) 3,3V TTL/CMOS signal level.

11 Hardware/Ordering Information

Part Number	Description	Operating Temperature Range	Note
ZU-09-038	SmartLED-IVB Converter BaseBoard	-30°C+80°C	1

Note 1:

Available configurations using SmartLED-Rover:

PWM = Frequency 100Hz-1000Hz, Duty 0% min. Brightness - 100% max. Brightness Signal level 3,3V or 5V Analog $_3$ 3V = 0V min. Brightness - 3,3V max. Brightness Analog $_5$ V = 0V min. Brightness - 5V max. Brightness Analog $_3$ 3V/Reverse = 3,3V min. Brightness - 0V max. Brightness Analog $_5$ V/Reverse = 5V min. Brightness - 0V max. Brightness

12 Application Notes

A combination of two different rail types is possible for NVIS applications; the active rail and corresponding current is selected via means of a digital trigger input, e.g.:

Trigger	Channel	Setting	Remarks
Low	1, 2	On, 200mA	Nia mara il mara da
(0V)	3, 4, 5, 6	Off	Normal mode
High	1, 2	Off	NIV/IOI-
(3.3V)	3, 4, 5, 6	On, 30mA	NVIS mode

12.1 Power Supply Selection

Using of grounded power supplies like Lite-On PA-1061 is necessary for safety and good EMC characteristics. An isolated power supply can help in mitigating the ground loops and reducing the visual artefacts like water fall noise, caused by sourcing via VGA input.

To prevent such visual artefacts, using of two separated grounded power supplies for the scaler board and the SmartLED-IVB is recommended.

13 Accessories

- Input Cable KA-20-100 for connecting to a standard Prisma Board.
- Adaptor Cable (panel/rail specific)
- Programming Interface for firmware update or configuration IF-370
- Sensors (ALS, Temperature Sensors): upon request



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